

Strutture dati per la Rappresentazione di Dati Vettoriali

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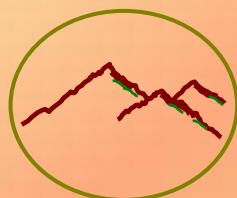
GE-IMATI-CNR



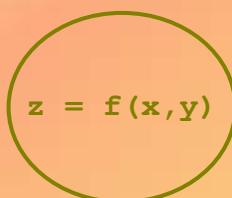
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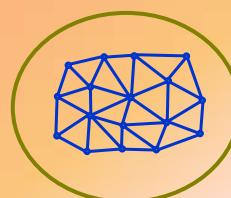
Geometric modelling



Physical world



Mathematical model



Digital representation

Idealization

Schematization

Basics on algebraic topology

- Algebraic topology associates algebraic invariants to each space so that two spaces are homeomorphic if they have same invariants
- Approach: to break a topological space into simple pieces that are easier to study (e.g. to decompose a polyhedron into faces, edges, vertices or a surface into triangles)

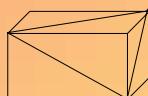
Basics on algebraic topology

- A combinatorial structure is generated decomposing the topological space
- Basic elements of the decomposition are cells or simplices that are characterized by
 - combinatorial aspects: relations among the cells of the complex
 - geometric aspects: which concern their embedding in the Euclidean space

Examples

- cells complexes

- a geographic map (which is formed by points, lines and regions)
 - the decomposition of a polyhedron into faces



- simplicial complexes

- triangle meshes



Abstract simplicial complex

- Let V a set. An abstract simplicial complex $\Sigma_A \subseteq \wp(V)$ is a set satisfying the following conditions:
 - $\emptyset \in \Sigma_A$,
 - $\forall v \in V, \{v\} \in \Sigma_A$,
 - $\sum \tau \subseteq \sigma \in \Sigma_A$, then $\tau \in \Sigma_A$
- e.g. $\{\{a,b,c\}, \{c,d\}, \{e\}\}$
- order = the maximum cardinality of the simplices
- any abstract simplicial complex of order d has a geometric realization in \mathbb{R}^{2d+1}

Geometric realization

- Let V_σ be a set of $d+1$ linearly independent points in the n -dimensional Euclidean space with $d \leq n$
- A d -simplex generated by V_σ is the subset of \mathbb{R}^n given by the points x that can be expressed as the convex combination of the points of V_σ

$$x = \sum_{i=0}^d l_i v_i \quad \text{with } l_i \in [0, 1] \text{ and } \sum_{i=0}^d l_i = 1$$

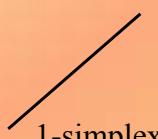
Examples

- d -simplices

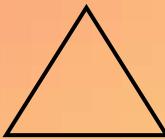
0-simplex



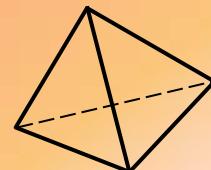
1-simplex



2-simplex



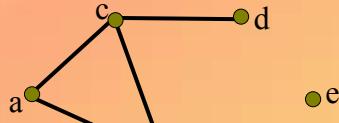
4-simplex



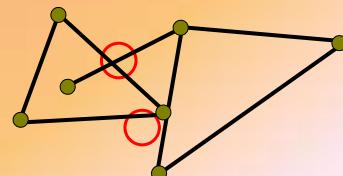
- Alternatively d -simplices may be defined as the convex hull of the points in V_σ

Simplicial complex

- realization of the simplex $\{\{a,b,c\}, \{c,d\}\}$:



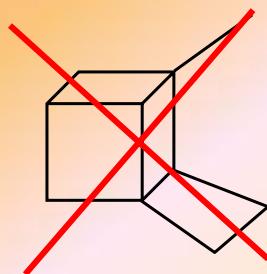
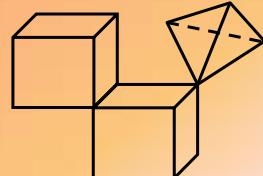
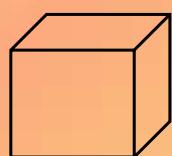
- a set of simplices may not be a simplicial complex:



Regular sets

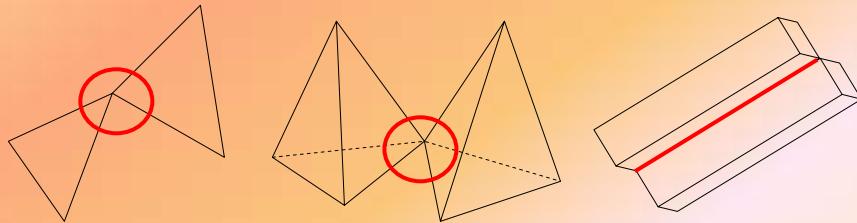
- A connected, compact set $A \subseteq \mathbb{R}^n$ is a *regular set* (*r-set*) if A equals the closure in \mathbb{R}^n of its interior:

$$c(i(A)) = A$$



Manifolds

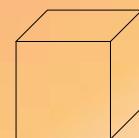
- In our case, when modelling a discrete space only r-sets with boundary 2-manifold will be considered



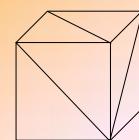
Euler characteristic

$$\chi(S) = v - e + f = 2(s - g) + h$$

- $v = \#$ vertices
- $e = \#$ edges
- $f = \#$ faces
- $S = \#$ connected components
- $g = \text{genus of the surface}$
- $h = \#$ boundary components

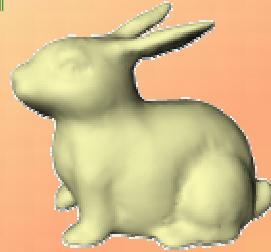


$$v=8, e=12, f=6$$

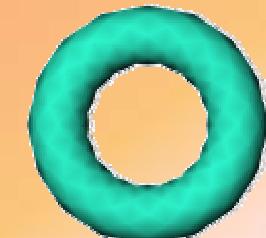


$$v=8, e=18, f=12$$

BUDDAH: v=32328, f=64676,
e=97014, holes=6, χ =-10



RABBIT: v=8500, f=16996,
e=25494, holes=0, χ =2



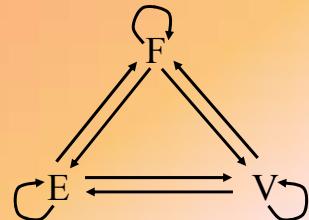
TORUS: v=256, f=512,
e=768, holes=1, χ =0

Representation schemes

- are relations which associate to a mathematical model a representation
- a representation must be
 - non ambiguous
 - unique
- boundary schemes represent a shape by describing its boundary

Data structures

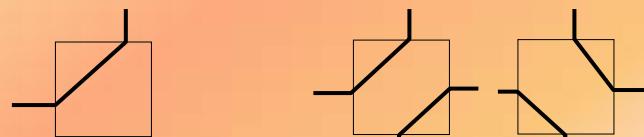
- topological relations of a boundary representation



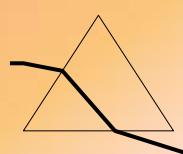
- time constant: EV, EE, EF
- time varying: VV, VE, VF, **FV, FE, FF**

Contour lines on square and triangle meshes

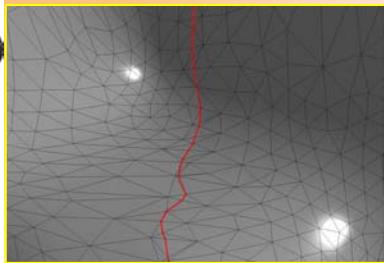
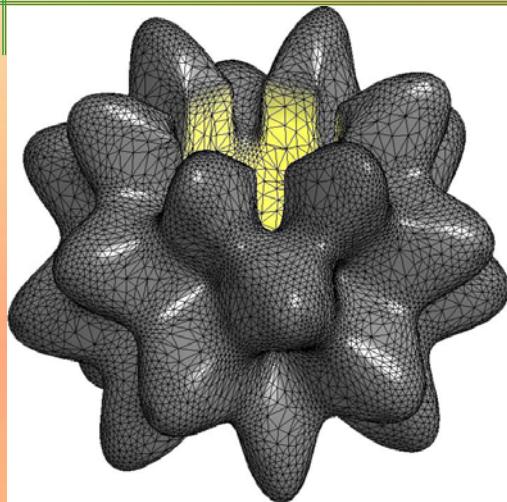
- square cells may have some ambiguities when contours are traced on the models



- triangle meshes overcome the ambiguity problem



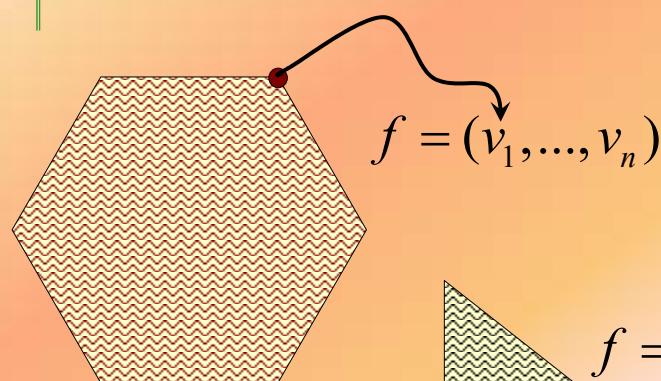
Coding and moving on simplicial complexes



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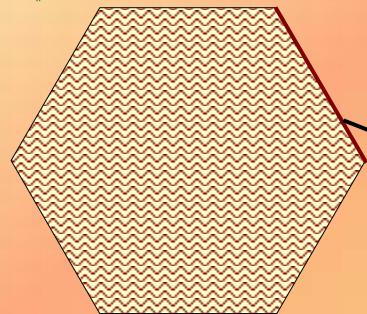
Face-Vertex: associates to a face the lists of its vertices



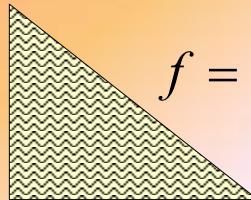
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Face-Edge: associates to a face the list of its edges

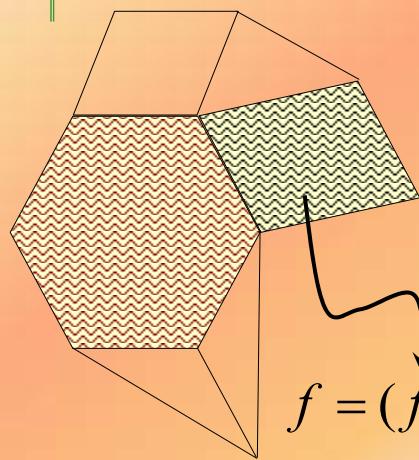


$$f = (e_1, \dots, e_n)$$

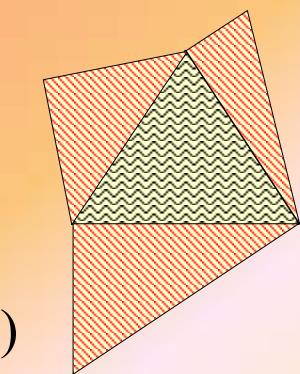


$$f = (e_1, e_2, e_3)$$

Face-Face: associates to a face the list of its adjacent faces

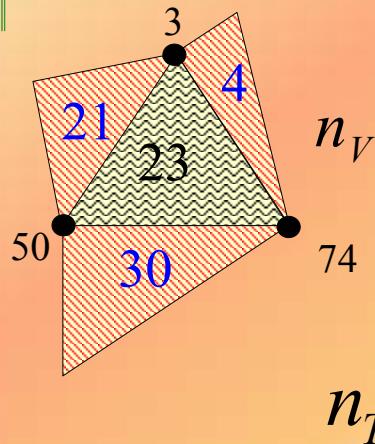


$$f = (f_1, \dots, f_n)$$



$$f = (f_1, f_2, f_3)$$

File Format & Input data structure



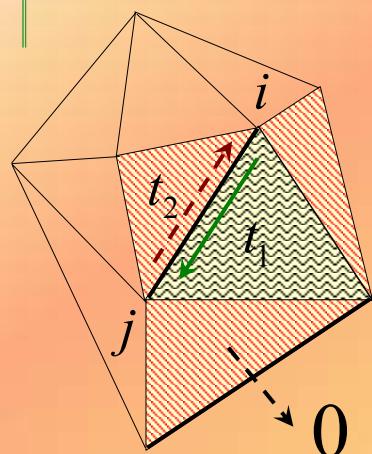
File (VER) : float/double

Row 3
Row 50 0.12 3.3 -0.34
Row 74

File (TRI) : integers

Row 22
Row 23 3 50 74 21 30 4
Row 24

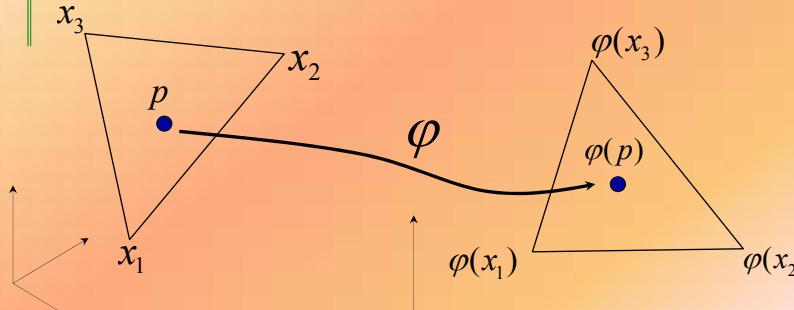
How to extract the face-face relation?



$$T \in M_{n_V, n_V} (\mathbb{Z})$$

$$T_{ij} = t_1, T_{ji} = t_2$$

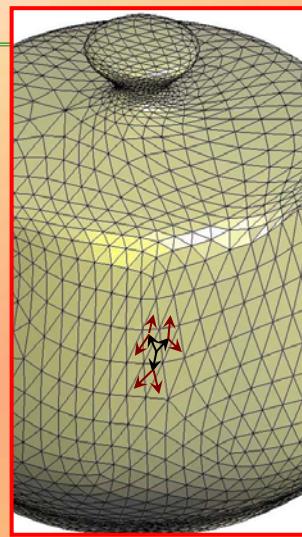
Barycentric coordinates



$$p = \lambda_1 x_1 + \lambda_2 x_2 + \lambda_3 x_3 \Leftrightarrow \varphi(p) = \lambda_1 \varphi(x_1) + \lambda_2 \varphi(x_2) + \lambda_3 \varphi(x_3)$$

$$\lambda_i \geq 0, i=1,2,3, \lambda_1 + \lambda_2 + \lambda_3 = 1$$

How to count the number of sheets?



Idea: use recursively the TT relation while marking triangles as visited and until the whole set of faces has been processed.

Computational cost: linear in the number of input triangles.

Esercitazione – Parte A: Superfici Triangolate

- 1. Scrivere una funzione di caricamento di un file OFF
[mat_ver,mat_tri]=load_off(file_name);
- 2. Usando la relazione FF, calcolare il numero di componenti connessi di una superficie triangolata arbitraria (con o senza bordo). Per ciascuna componente connessa (shell) estrarne:
 - le (eventuali) componenti di bordo;
 - il genere;
 - l'area.

```
shell=extract_shells(mat_tri);
```